ANEXO 8 – Descrição do formato RINEX;

10-December 2007 |

RINEX: The Receiver Independent Exchange Format Version 2.10
****

Werner Gurtner
Astronomical Institute
University of Berne

Contents:
****

0. REVISION HISTORY

0.1 Revision Summary

First Revision, April 1993
Clarification December 1993
Doppler Definition: January 1994
PR Clarification: October 1994
Wlfact Clarification: February 1995
Event Time Frame Clarification: May 1996
Minor errors in the examples A7/A8: May 1996
Naming convention for compressed met files; January 1997
Continuation line clarifications: April 1997
GLONASS Extensions: April 1997
Met sensor description and position records: April 1997
Wavelength factor clarifications: April 1997
Error in example A12: CORR TO SYSTEM TIME, April 1997
Redefinition of sv clock params in GLONASS Nav Mess Files: March 1998
Naming conventions for compressed RINEX obs files: March 1998
GPS week: No roll-over, continuous number: March 1998
Error in compressed DOS file naming convention: July 1998
Table A13 contained blank satellite identifiers: Sept 1998
Discrepancy between Tables A5 and A9 removed: Sept 1998
Phase data format overflow: Clarification: Oct 1998
Message frame time Table A11: Clarification: Oct 1998
RINEX Version 2.10 Modifications: July 1999
Typo in paragraph 0.4 (epoch flag >1): Nov 1999
Clarification regarding trailing blanks: Dec 1999
Clarification regarding units of ZD,ZT, URA(GEO)
Clarification regarding time system identifier of GEO obs files
Clarification regarding time system identifier in TIME OF LAST record: Feb 2000
Addition of GEO examples: February 2000
Clarification of epoch field for event flag records: May 2000
Table A6: Typos in format definition of epoch: May 2000
Clarification of the GLONASS satellite identifier: June 2001
Clarification of the floating point exponent format: January 2002
Glonass frequency numbers -7 ... +13: December 2007 |

0.2 First Revision

The first documentation of the RINEX Version 2 Format was published by
W. Gurtner and G. Mader in the CSTG GPS Bulletin of September/October 1990.
The main reason for a revision is the new treatment of antispoofing data by
the RINEX format (see chapter 7). Chapter 4 gives a recommendation for data
compression procedures, especially useful when large amounts of data are
exchanged through computer networks. In Table A3 in the original paper the
definiton of the "PGM / RUN BY / DATE" navigation header record was
missing, although the example showed it. The redefinition of AODE/AODC to
IODE/IODC also asked for an update of the format description. For consistency
reasons we also defined a Version 2 format for the Meteorological Data files
(inclusion of a END OF HEADER record and an optional MARKER NUMBER record).

The slight modification (or rather the definition of a bit in the Loss of Lock Indicator unused so far) to flag AS data is so small a change that we decided to NOT increase the version number!

0.3 Later Revisions

* URA Clarification (10-Dec-93):

  The user range accuracy in the Navigation Message File did not contain a definition of the units: There existed two ways of interpretation: Either the 4 bit value from the original message or the converted value in meters according to GPS ICD-200. In order to simplify the interpretation for the user of the RINEX files I propose the bits to be converted into meters prior to RINEX file creation.

* GLONASS Extensions:

  In March 1997 a proposal for extensions to the current RINEX definitions based on experiences collected with GLONASS only and mixed GPS/GLONASS data files was circulated among several instrument manufacturers and software developers.

  The results of the call for comments have been worked into this document. A separate document (glonass.txt) summarizes just the necessary extensions.

* A blank satellite identifier is allowed in pure GPS files only

* Met sensor description and position records were added to facilitate the precise use of met values.

* Description and examples for wavelength factors and their temporary changes (bit 1 of LLI) clarified.

* The RINEX documentation distributed in spring 1997 contained definitions for the GLONASS satellite clock offset and drift with the intention to have them defined identically to the GPS values. Unfortunately the GLONASS Interface Document consulted had a sign error in one of the formulae.

  The values should be stored into the RINEX file as -TauN, +GammaN, -TauC. The original definition asked for -TauN, -GammaN, +TauC. See paragraph 8.2.

  To avoid problems with files created with the original definitions a real valued version number (2.01) has been introduced for GLONASS nav mess files.

* IGS decided to use the Hatanaka compression scheme for RINEX observation files. Below the corresponding RINEX file name conventions are included as recommendations. The DOS naming (extension .yyE) was wrongly set to .yyY in the March 1998 version of the document.

* GPS week: The GPS week number in all RINEX files is a continuous number not affected by the 1024 roll-over, it runs from 1023 over 1024 to 1025 etc.

* A descrepancy between the definition of the header line fields of met sensor description and position in Table A5 and the example in Table A9 was removed. The latter was correct.

* Clarification for phase data format overflows: Add or subtract a suitable number of cycles, set LLI flag.

* Clarification for the GLONASS satellite identifier: "Almanac number" was somewhat ambiguous. It has been replaced by "slot number" within the satellite constellation.

0.4 Version 2.10 Modifications

The modifications leading to Version 2.10 include:

- Fractional version number
- Zero padding of 2-digit year values (years 2000-2009 --> 00-09)
- Field length of time of first obs (1/10 microsecond resolution)
- Non-integer sampling rate (INTERVAL header record)
- Header records now allowed after all epoch flags >1
- Additional obs types in obs files: S1, S2 (raw signal strength values)
- Receiver clock offset header line to clarify applied corrections
- Default wavelength factor header line mandatory
- Inmarsat GPS payloads: New satellite system definition, new nav mess files
- Curve fit interval in GPS nav mess file
- Redefinition of SV health value in GPS nav mess file
- Additional obs types in met files (ZD, ZT)

0.5 Version 2.10 Revisions

* "Header records now allowed after all epoch flags >2" in paragraph 0.4
  should read ">1"

* The original intention of the RINEX format was to allow for variable record
  lengths of the ASCII files to minimize the file size. Empty fields or
  unknown values can either be represented by zeroes or blank space. Most
  RINEX converters removed trailing blank to further reduce the file size. The
  documentation was not clear enough to explicitely allow for this practice
  (paragraphs 2, 5.3, 9.1).

* The time system identifier of GPS observations generated by GEO payloads
  defaults to GPS (explicitly stated now in paragraph 9.1)

* The time system identifier in the TIME OF LAST OBS header record has to
  be identical to the one in the TIME OF FIRST OBS record

* Clarification of Table A2 to be compatible with examples of Table A7:
  For event flags without significant epoch the epoch fields can be left blank.
  Table A6: Format for epoch contained obvious errors

* Clarification of the floating point exponent format in navigation message
  files (two digits, E,e,D,d letters)

* The newer GLONASS satellites started using frequency numbers in the 0 to
  -7 range. Table A11 BROADCAST ORBIT - 2 was modified accordingly.

1. THE PHILOSOPHY OF RINEX

The first proposal for the "Receiver Independent Exchange Format" RINEX has
been developed by the Astronomical Institute of the University of Berne for
the easy exchange of the GPS data to be collected during the large European
GPS campaign EUREF 89, which involved more than 60 GPS receivers of 4
different manufacturers. The governing aspect during the development was
the following fact:

Most geodetic processing software for GPS data use a well-defined set of
observables:

- the carrier-phase measurement at one or both carriers (actually being a
measurement on the beat frequency between the received carrier of the
satellite signal and a receiver-generated reference frequency).

- the pseudorange (code) measurement, equivalent to the difference of the
time of reception (expressed in the time frame of the receiver) and the
time of transmission (expressed in the time frame of the satellite) of a
distinct satellite signal.

- the observation time being the reading of the receiver clock at the

instant of validity of the carrier-phase and/or the code measurements.

Usually the software assumes that the observation time is valid for both the phase AND the code measurements, AND for all satellites observed.

Consequently all these programs do not need most of the information that is usually stored by the receivers: They need phase, code, and time in the above mentioned definitions, and some station-related information like station name, antenna height, etc.

2. GENERAL FORMAT DESCRIPTION

Currently the format consists of six ASCII file types:

1. Observation Data File
2. Navigation Message File
3. Meteorological Data File
4. GLONASS Navigation Message File
5. GEO Navigation Message File
6. Satellite and Receiver Clock Date File

(The format definition of the clock files has been published in 1998 in a separate document by Jim Ray and Werner Gurtner, available at the IGS Central Bureau Information System: ftp://igscb.jpl.nasa.gov/igscb/data/format/rinex_clock.txt).

Each file type consists of a header section and a data section. The header section contains global information for the entire file and is placed at the beginning of the file. The header section contains header labels in columns 61-80 for each line contained in the header section. These labels are mandatory and must appear exactly as given in these descriptions and examples.

The format has been optimized for mimimum space requirements independent from the number of different observation types of a specific receiver by indicating in the header the types of observations to be stored. In computer systems allowing variable record lengths the observation records may be kept as short as possible. Trailing blanks can be removed from the records. The maximum record length is 80 bytes per record.

Each Observation file and each Meteorological Data file basically contain the data from one site and one session. RINEX Version 2 also allows to include observation data from more than one site subsequently occupied by a roving receiver in rapid static or kinematic applications. Although Version 2 allows to insert header records into the data field we do not recommend to concatenate data of more than one receiver (or antenna) into the same file, even if the data do not overlap in time.

If data from more than one receiver has to be exchanged it would not be economical to include the identical satellite messages collected by the different receivers several times. Therefore the Navigation Message File from one receiver may be exchanged or a composite Navigation Message File created containing non-redundant information from several receivers in order to make the most complete file.

The format of the data records of the RINEX Version 1 Navigation Message file is identical to the former NGS exchange format.

The actual format descriptions as well as examples are given in the Tables at the end of the paper.

3. DEFINITION OF THE OBSERVABLES

GPS observables include three fundamental quantities that need to be defined: Time, Phase, and Range.

TIME:

The time of the measurement is the receiver time of the received signals. It is identical for the phase and range measurements and is identical for all satellites observed at that epoch. It is expressed in GPS time (not Universal Time).

PSEUDO-RANGE:

The pseudo-range (PR) is the distance from the receiver antenna to the satellite antenna including receiver and satellite clock offsets (and other biases, such as atmospheric delays):

```
PR  =  distance +
       c * (receiver clock offset - satellite clock offset +
            other biases)
```

so that the pseudo-range reflects the actual behavior of the receiver and satellite clocks. The pseudo-range is stored in units of meters. See also clarifications for pseudoranges in mixed GPS/GLONASS files in chapter 8.1.

PHASE:

The phase is the carrier-phase measured in whole cycles at both L1 and L2. The half-cycles measured by sqaring-type receivers must be converted to whole cycles and flagged by the wavelength factor in the header section.
The phase changes in the same sense as the range (negative doppler). The phase observations between epochs must be connected by including the integer number of cycles. The phase observations will not contain any systematic drifts from intentional offsets of the reference oscillators.

The observables are not corrected for external effects like atmospheric refraction, satellite clock offsets, etc.
If the receiver or the converter software adjusts the measurements using the real-time-derived receiver clock offsets dT(r), the consistency of the 3 quantities phase / pseudo-range / epoch must be maintained, i.e. the receiver clock correction should be applied to all 3 observables:

```
Time(corr)  = Time(r)  -  dT(r)
PR(corr)    =  PR(r)   -  dT(r)*c
phase(corr) = phase(r) -  dT(r)*freq
```

DOPPLER:

The sign of the doppler shift as additional observable is defined as usual: Positive for approaching satellites.

4. THE EXCHANGE OF RINEX FILES:

We recommend using the following naming convention for RINEX files:

```
        ssssdddf.yyt      ssss:    4-character station name designator
                           ddd:    day of the year of first record
                             f:    file sequence number within day
                                   0: file contains all the existing
                                      data of the current day
                            yy:    year
                             t:    file type:
                                   O: Observation file
                                   N: Navigation file
                                   M: Meteorological data file
                                   G: GLONASS Navigation file
                                   H: Geostationary GPS payload nav mess file
                                   B: Geostationary GPS payload broadcast data
                                   C: Clock files (see separate documentation)
```

When data transmission times or storage volumes are critical we recommend compressing the files prior to storage or transmission using the UNIX "compress" und "uncompress" programs. Compatible routines are available on VAX/VMS and PC/DOS systems, as well.

Proposed naming conventions for the compressed files:

File Types	UNIX	VMS	DOS
Obs Files	ssssdddf.yyO.Z	ssssdddf.yyO_Z	ssssdddf.yyY
Obs Files (Hatanaka compr)	ssssdddf.yyD.Z	ssssdddf.yyD_Z	ssssdddf.yyE
GPS Nav Files	ssssdddf.yyN.Z	ssssdddf.yyN_Z	ssssdddf.yyX
GLONASS Nav File	ssssdddf.yyG.Z	ssssdddf.yyG_Z	ssssdddf.yyV
GEO Nav Files	ssssdddf.yyH.Z	ssssdddf.yyH_Z	ssssdddf.yyU
GEO Broadcast Files	ssssdddf.yyB.Z	ssssdddf.yyB_Z	
Met Data Files	ssssdddf.yyM.Z	ssssdddf.yyM_Z	ssssdddf.yyW
Clock Files (see sep.doc.)	ssssdddf.yyC.Z	ssssdddf.yyC_Z	

References for the Hatanaka compression scheme: See e.g.

ftp://igscb.jpl.nasa.gov/igscb/software/rnxcmp/docs/

IGSMails 1525,1686,1726,1763,1785

5. RINEX VERSION 2 FEATURES

The following section contains features that have been introduced for RINEX Version 2:

5.1 Satellite Numbers:

Version 2 has been prepared to contain GLONASS or other satellite systems' observations. Therefore we have to be able to distinguish the satellites of the different systems: We precede the 2-digit satellite number with a system identifier.

snn

s: satellite system identifier
- G or blank : GPS
- R : GLONASS
- S : Geostationary signal payload
- T : Transit

nn:
- PRN (GPS), slot number (GLONASS)
- PRN-100 (GEO)
- two-digit Transit satellite number

Note: G is mandatory in mixed GPS/GLONASS files

(blank default modified in April 1997)

5.2 Order of the Header Records:

As the record descriptors in columns 61-80 are mandatory, the programs reading a RINEX Version 2 header are able to decode the header records with formats according to the record descriptor, provided the records have been first read into an internal buffer.

We therefore propose to allow free ordering of the header records, with the following exceptions:

- The "RINEX VERSION / TYPE" record must be the first record in a file

- The default "WAVELENGTH FACT L1/2" record must precede all records defining wavelength factors for individual satellites

- The "# OF SATELLITES" record (if present) should be immediately followed by the corresponding number of "PRN / # OF OBS" records. (These records may be handy for documentary purposes. However, since they may only be created after having read the whole raw data file we define them to be optional.

5.3 Missing Items, Duration of the Validity of Values

Items that are not known at the file creation time can be set to zero or blank or the respective record may be completely omitted. Consequently items of missing header records will be set to zero or blank by the program reading RINEX files. Trailing blanks may be truncated from the record.

Each value remains valid until changed by an additional header record.

5.4 Event Flag Records

The "number of satellites" also corresponds to the number of records of the same epoch followed. Therefore it may be used to skip the appropriate number of records if certain event flags are not to be evaluated in detail.

5.5 Receiver Clock Offset

A large number of users asked to optionally include a receiver-derived clock offset into the RINEX format. In order to remove uncertainties if the data (epoch, pseudorange, phase) have been previously corrected or not by the reported clock offset, RINEX Version 2.10 requests a clarifying (new) header record.

It would then be possible to reconstruct the original observations if necessary.

As the output format for the receiver-derived clock offset is limited to nanoseconds the offset should be rounded to the nearest nanosecond before it is used to correct the observables in order to guarantee correct reconstruction.

6. ADDITIONAL HINTS AND TIPS

6.1 Version 1 / Version 2

Programs developed to read RINEX Version 1 files have to verify the version number. Version 2 files may look different (version number, END OF HEADER record, receiver and antenna serial number alphanumeric) even if they do not use any of the new features

6.2 Leading Blanks in CHARACTER fields

We propose that routines to read RINEX Version 2 files automatically delete leading blanks in any CHARACTER input field. Routines creating RINEX Version 2 files should also left-justify all variables in the CHARACTER fields.

6.3 Variable-length Records

DOS, and other, files may have variable record lengths, so we recommend to first read each observation record into a 80-character blank string and decode the data afterwards. In variable length records, empty data fields at the end of a record may be missing, especially in the case of the optional receiver clock offset.

6.4 Blank Fields

In view of future modifications we recommend to carefully skip any fields currently defined to be blank (Format fields nX), because they may be assigned to new contents in future versions.

6.5 2-Digit Years

RINEX version 2 stores the years of data records with two digits only. The header of observation files contains a TIME OF FIRST OBS record with the full four-digit year, the GPS nav messages contain the GPS week numbers. From these two data items the unambiguous year can easily be reconstructed.

A hundred-year ambiguity occurs in the met data and GLONASS and GEO nav messages: Instead of introducing a new TIME OF FIRST OBS header line it is safeto stipulate that any two-digit years in RINEX Version 1 and Version 2.xx files are understood to represent

```
80-99:  1980-1999
00-79:  2000-2079
```

Full 4-digit year fields could then be defined by a future RINEX version 3.

6.6 Fit Interval

Bit 17 in word 10 of subframe 2 is a "fit interval" flag which indicates the curve-fit interval used by the GPS Control Segment in determining the ephemeris parameters, as follows (see ICD-GPS-200, 20.3.3.4.3.1):

```
0 = 4 hours
1 = greater than 4 hours.
```

Together with the IODC values and Table 20-XII the actual fit interval can be determined. The second value in the last record of each message shall contain the fit interval in hours determined using IODC, fit flag, and Table 20-XII, according to the Interface Document ICD-GPS-200.

6.7 Satellite Health

The health of the signal components (bits 18 to 22 of word three in subframe one) are now (Version 2.10) included into the health value reported in the second field of the sixth nav mess records.

A program reading RINEX files could easily decide if bit 17 only or all bits (17-22) have been written:

```
RINEX Value:   0    Health OK
RINEX Value:   1    Health not OK (bits 18-22 not stored)
RINEX Value: >32    Health not OK (bits 18-22 stored)
```

6.8 Transmission Time of Message (Navigation message file)

The transmission time of message can be shortly before midnight Saturday/Sunday, the TOE and TOC of the message already in the next week. As the reported week in the RINEX nav message (BROADCAST ORBIT - 5 record) goes with ToE (this is different from the GPS week in the original satellite message!), the transmission time of message should be reduced by 604800 (i.e., will become negative) to also refer to the same week.

7. RINEX UNDER ANTISPOOFING (AS)

Some receivers generate code delay differences between the first and second frequency using cross-correlation techniques when AS is on and may recover

the phase observations on L2 in full cycles. Using the C/A code delay on L1 and the observed difference it is possible to generate a code delay observation for the second frequency.

Other receivers recover P code observations by breaking down the Y code into P and W code.

Most of these observations may suffer from an increased noise level. In order to enable the postprocessing programs to take special actions, such AS-infected observations are flagged using bit number 2 of the Loss of Lock Indicators (i.e. their current values are increased by 4).

8. GLONASS Extensions

8.1 RINEX Observation File

8.1.1 Time System Identifier

The original RINEX Version 2 needed one major supplement, the explicit definition of the time system:

GLONASS is basically running on UTC (or, more precisely, GLONASS system time linked to UTC(SU)), i.e. the time tags are given in UTC and not GPS time. In order to remove possible misunderstandings and ambiguities, the header records "TIME OF FIRST OBS" and (if present) "TIME OF LAST OBS" in GLONASS and GPS observation files _can_, in mixed GLONASS/GPS observation files _must_ contain a time system identifier defining the system that all time tags in the file are referring to: "GPS" to identify GPS time, "GLO" to identify the GLONASS UTC time system. Pure GPS files default to GPS and pure GLONASS files default to GLO.

Format definitions see Table A1.

Hence, the two possible time tags differ by the current number of leap seconds.

In order to have the current number of leap seconds available we recommend to include a LEAP SECOND line into the RINEX header.

If there are known non-integer biases between the "GPS receiver clock" and "GLONASS receiver clock" in the same receiver, they should be applied. In this case the respective code and phase observations have to be corrected, too (c * bias if expressed in meters).

Unknown such biases will have to be solved for during the post processing

The small differences (modulo 1 second) between GLONASS system time, UTC(SU), UTC(USNO) and GPS system time have to be dealt with during the post-processing and not before the RINEX conversion. It may also be necessary to solve for remaining differences during the post-processing.

8.1.2 Pseudorange Definition

The pseudorange (code) measurement is defined to be equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal.

If a mixed-mode GPS/GLONASS receiver refers all pseudorange observations to one receiver clock only,

- the raw GLONASS pseudoranges will show the current number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GPS time frame

- the raw GPS pseudoranges will show the negative number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GLONASS time frame

In order to avoid misunderstandings and to keep the code observations within the format fields, the pseudoranges must be corrected in this case as follows:

```
  PR(GPS) := PR(GPS) + c * leap_seconds   if generated with a receiver clock
                                          running in the GLONASS time frame

  PR(GLO) := PR(GLO) - c * leap_seconds   if generated with a receiver clock
                                          running in the GPS time frame
```

to remove the contributions of the leap seconds from the pseudoranges.

"leap_seconds" is the actual number of leap seconds between GPS and GLONASS (UTC) time, as broadcast in the GPS almanac and distributed in Circular T of BIPM.

8.1.3 More Than 12 Satellites per Epoch

The format of the epoch / satellite line in the observation record part of the RINEX Observation files has only been defined for up to 12 satellites per epoch. We explicitly define now the format of the continuation lines, see Table A2.

8.2 RINEX Navigation Files for GLONASS

As the GLONASS navigation message differs in contents from the GPS message too much, a special GLONASS navigation message file format has been defined.

The header section and the first data record (epoch, satellite clock information) is similar to the GPS navigation file. The following records contain the satellite position, velocity and acceleration, the clock and frequency biases as well as auxiliary information as health, satellite frequency (channel), age of the information.

The corrections of the satellite time to UTC are as follows:

```
  GPS    : Tutc = Tsv - af0  -  af1  *(Tsv-Toc) - ... -  A0  - ... - leap_sec
  GLONASS: Tutc = Tsv + TauN - GammaN*(Tsv-Tb)        + TauC
```

*** In order to use the same sign conventions for the GLONASS corrections as in the GPS navigation files, the broadcast GLONASS values are stored as:

-TauN, +GammaN, -TauC.

The time tags in the GLONASS navigation files are given in UTC (i.e. _not_ Moscow time or GPS time).

Filenaming convention: See above.

9. RINEX Extensions for Geostationary Satellites (GPS Signal Payloads)

With the implementation of GNSS programs, GPS-like ranging measurements can be performed on geostationary navigation payloads.

RINEX Version 2.10 defines the necessary extensions to handle such data in RINEX files for data exchange and postprocessing purposes.

9.1 RINEX Observation Files for GEO Satellites

A new satellite system identifier has been defined for the geostationary GPS signal payloads: "S", to be used in the RINEX VERSION / TYPE header line and in the satellite identifier 'snn', nn being the GEO PRN number minus 100.

e.g.: PRN = 120 --> 'snn' = "S20"

In mixed dual frequency GPS satellite / single frequency GEO payload observation files the fields for the second frequency observations of GEO satellites remain blank, are set to zero values or (if last in the record) can be truncated.

The time system identifier of GEO satellites generating GPS signals defaults to GPS time.

9.2 RINEX Navigation Message Files for GEO Satellites

As the GEO broadcast orbit format differs from the GPS message a special GEO navigation message file format has been defined which is nearly identical with the GLONASS nav mess file format.

The header section contains informations about the generating program, comments, and the difference between the GEO system time and UTC.

The first data record contains the epoch and satellite clock information, the following records contain the satellite position, velocity and acceleration and auxiliary information such as health, age of the data, etc.

The time tags in the GEO navigation files are given in the GPS time frame, i.e. not UTC.

The corrections of the satellite time to UTC are as follows:

```
  GEO    : Tutc = Tsv - aGf0  -  aGf1 *(Tsv-Toe) -  W0  - leap_sec
```

W0 being the correction to transform the GEO system time to UTC. Toe, aGf0, aGf1 see below in the format definition tables.

```
*  References for the definition of the accuracy and health codes still have *
*  to be defined.                                                             *
*  Help is needed here by colleagues working with such GEO data!              *
```

10. REFERENCES

Evans, A. (1989): "Summary of the Workshop on GPS Exchange Formats." Proceedings of the Fifth International Geodetic Symposium on Satellite Systems, pp. 917ff, Las Cruces.

Gurtner, W., G. Mader, D. Arthur (1989): "A Common Exchange Format for GPS Data." CSTG GPS Bulletin Vol.2 No.3, May/June 1989, National Geodetic Survey, Rockville.

Gurtner, W., G. Mader (1990): "The RINEX Format: Current Status, Future Developments." Proceedings of the Second International Symposium of Precise Positioning with the Global Positioning system, pp. 977ff, Ottawa.

Gurtner, W., G. Mader (1990): "Receiver Independent Exchange Format Version 2." CSTG GPS Bulletin Vol.3 No.3, Sept/Oct 1990, National Geodetic Survey, Rockville.

Gurtner, W. (1994): "RINEX: The Receiver-Independent Exchange Format." GPS World, Volume 5, Number 7, July 1994.

11. RINEX VERSION 2.10 FORMAT DEFINITIONS AND EXAMPLES

TABLE A1

GPS OBSERVATION DATA FILE - HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT

RINEX VERSION / TYPE	- Format version (2.10) - File type ('O' for Observation Data) - Satellite System: blank or 'G': GPS 'R': GLONASS 'S': Geostationary signal payload 'T': NNSS Transit 'M': Mixed	F9.2,11X, A1,19X, A1,19X	
PGM / RUN BY / DATE	- Name of program creating current file - Name of agency creating current file - Date of file creation	A20, A20, A20	
* COMMENT	Comment line(s)	A60	*
MARKER NAME	Name of antenna marker	A60	
* MARKER NUMBER	Number of antenna marker	A20	*
OBSERVER / AGENCY	Name of observer / agency	A20,A40	
REC # / TYPE / VERS	Receiver number, type, and version (Version: e.g. Internal Software Version)	3A20	
ANT # / TYPE	Antenna number and type	2A20	
APPROX POSITION XYZ	Approximate marker position (WGS84)	3F14.4	
ANTENNA: DELTA H/E/N	- Antenna height: Height of bottom surface of antenna above marker - Eccentricities of antenna center relative to marker to the east and north (all units in meters)	3F14.4	
WAVELENGTH FACT L1/2	- Default wavelength factors for L1 and L2 1: Full cycle ambiguities 2: Half cycle ambiguities (squaring) 0 (in L2): Single frequency instrument - zero or blank The default wavelength factor line is required and must preceed satellite-specific lines.	2I6, I6	
* WAVELENGTH FACT L1/2	- Wavelength factors for L1 and L2 1: Full cycle ambiguities 2: Half cycle ambiguities (squaring) 0 (in L2): Single frequency instrument - Number of satellites to follow in list for which these factors are valid. - List of PRNs (satellite numbers with system identifier) These opional satellite specific lines may follow, if they identify a state different from the default values. Repeat record if necessary.	2I6, I6, 7(3X,A1,I2)	*
# / TYPES OF OBSERV	- Number of different observation types stored in the file - Observation types If more than 9 observation types: Use continuation line(s)	I6, 9(4X,A2) 6X,9(4X,A2)	

	The following observation types are defined in RINEX Version 2.10: L1, L2: Phase measurements on L1 and L2 C1 : Pseudorange using C/A-Code on L1 P1, P2: Pseudorange using P-Code on L1,L2 D1, D2: Doppler frequency on L1 and L2 T1, T2: Transit Integrated Doppler on 150 (T1) and 400 MHz (T2) S1, S2: Raw signal strengths or SNR values as given by the receiver for the L1,L2 phase observations Observations collected under Antispoofing are converted to "L2" or "P2" and flagged with bit 2 of loss of lock indicator (see Table A2). Units : Phase : full cycles Pseudorange : meters Doppler : Hz Transit : cycles SNR etc : receiver-dependent The sequence of the types in this record has to correspond to the sequence of the observations in the observation records		
*	INTERVAL	Observation interval in seconds	F10.3	*
	TIME OF FIRST OBS	- Time of first observation record (4-digit-year, month,day,hour,min,sec) - Time system: GPS (=GPS time system) GLO (=UTC time system) Compulsory in mixed GPS/GLONASS files Defaults: GPS for pure GPS files GLO for pure GLONASS files	5I6,F13.7, 5X,A3	
*	TIME OF LAST OBS	- Time of last observation record (4-digit-year, month,day,hour,min,sec) - Time system: Same value as in TIME OF FIRST OBS record	5I6,F13.7, 5X,A3	*
*	RCV CLOCK OFFS APPL	Epoch, code, and phase are corrected by applying the realtime-derived receiver clock offset: 1=yes, 0=no; default: 0=no Record required if clock offsets are reported in the EPOCH/SAT records	I6	*
*	LEAP SECONDS	Number of leap seconds since 6-Jan-1980 Recommended for mixed GPS/GLONASS files	I6	*
*	# OF SATELLITES	Number of satellites, for which observations are stored in the file	I6	*
*	PRN / # OF OBS	PRN (sat.number), number of observations for each observation type indicated in the "# / TYPES OF OBSERV" - record. If more than 9 observation types: Use continuation line(s) This record is (these records are) repeated for each satellite present in the data file	3X,A1,I2,9I6 6X,9I6	*
	END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A2
GPS OBSERVATION DATA FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
EPOCH/SAT or EVENT FLAG	- Epoch :	
	- year (2 digits, padded with 0 if necessary)	1X,I2.2,
	- month,day,hour,min,	4(1X,I2),
	- sec	F11.7,
	- Epoch flag 0: OK	2X,I1,
	1: power failure between previous and current epoch	
	>1: Event flag	
	- Number of satellites in current epoch	I3,
	- List of PRNs (sat.numbers with system identifier, see 5.1) in current epoch	12(A1,I2),
	- receiver clock offset (seconds, optional)	F12.9
	If more than 12 satellites: Use continuation line(s)	32X, 12(A1,I2)
	If epoch flag 2-5:	
	- Event flag:	[2X,I1,]
	2: start moving antenna	
	3: new site occupation (end of kinem. data) (at least MARKER NAME record follows)	
	4: header information follows	
	5: external event (epoch is significant, same time frame as observation time tags)	
	- "Number of satellites" contains number of special records to follow. Maximum number of records: 999	[I3]
	- For events without significant epoch the epoch fields can be left blank	
	If epoch flag = 6:	
	6: cycle slip records follow to optionally report detected and repaired cycle slips (same format as OBSERVATIONS records; slip instead of observation; LLI and signal strength blank or zero)	
OBSERVATIONS	- Observation | rep. within record for - LLI | each obs.type (same seq - Signal strength | as given in header)	m(F14.3, I1, I1)
	If more than 5 observation types (=80 char): continue observations in next record.	
	This record is (these records are) repeated for each satellite given in EPOCH/SAT - record.	
	Observations: Phase : Units in whole cycles of carrier Code : Units in meters Missing observations are written as 0.0 or blanks.	
	Phase values overflowing the fixed format F14.3	

	have to be clipped into the valid interval (e.g. add or subtract 10**9), set LLI indicator.	
	Loss of lock indicator (LLI). Range: 0-7 0 or blank: OK or not known Bit 0 set : Lost lock between previous and current observation: cycle slip possible Bit 1 set : Opposite wavelength factor to the one defined for the satellite by a previous WAVELENGTH FACT L1/2 line. Valid for the current epoch only. Bit 2 set : Observation under Antispoofing (may suffer from increased noise) Bits 0 and 1 for phase only.	
	Signal strength projected into interval 1-9: 1: minimum possible signal strength 5: threshold for good S/N ratio 9: maximum possible signal strength 0 or blank: not known, don't care	

TABLE A3

GPS NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION

	HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
	RINEX VERSION / TYPE	- Format version (2.10) - File type ('N' for Navigation data)	F9.2,11X, A1,19X
	PGM / RUN BY / DATE	- Name of program creating current file - Name of agency creating current file - Date of file creation	A20, A20, A20
*	COMMENT	Comment line(s)	A60
*	ION ALPHA	Ionosphere parameters A0-A3 of almanac (page 18 of subframe 4)	2X,4D12.4
*	ION BETA	Ionosphere parameters B0-B3 of almanac	2X,4D12.4
*	DELTA-UTC: A0,A1,T,W	Almanac parameters to compute time in UTC (page 18 of subframe 4) A0,A1: terms of polynomial T : reference time for UTC data W : UTC reference week number. Continuous number, not mod(1024)!	3X,2D19.12, 2I9 *)
*	LEAP SECONDS	Delta time due to leap seconds	I6
	END OF HEADER	Last record in the header section.	60X

Records marked with * are optional

TABLE A4

GPS NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite PRN number	I2,

	- Epoch: Toc - Time of Clock	
	year (2 digits, padded with 0	
	if necessary)	1X,I2.2,
	month	1X,I2,
	day	1X,I2,
	hour	1X,I2,
	minute	1X,I2,
	second	F5.1,
	- SV clock bias (seconds)	3D19.12
	- SV clock drift (sec/sec)	
	- SV clock drift rate (sec/sec2)	*)
BROADCAST ORBIT - 1	- IODE Issue of Data, Ephemeris	3X,4D19.12
	- Crs (meters)	
	- Delta n (radians/sec)	
	- M0 (radians)	
BROADCAST ORBIT - 2	- Cuc (radians)	3X,4D19.12
	- e Eccentricity	
	- Cus (radians)	
	- sqrt(A) (sqrt(m))	
BROADCAST ORBIT - 3	- Toe Time of Ephemeris	3X,4D19.12
	(sec of GPS week)	
	- Cic (radians)	
	- OMEGA (radians)	
	- CIS (radians)	
BROADCAST ORBIT - 4	- i0 (radians)	3X,4D19.12
	- Crc (meters)	
	- omega (radians)	
	- OMEGA DOT (radians/sec)	
BROADCAST ORBIT - 5	- IDOT (radians/sec)	3X,4D19.12
	- Codes on L2 channel	
	- GPS Week # (to go with TOE)	
	Continuous number, not mod(1024)!	
	- L2 P data flag	
BROADCAST ORBIT - 6	- SV accuracy (meters)	3X,4D19.12
	- SV health (bits 17-22 w 3 sf 1)	
	- TGD (seconds)	
	- IODC Issue of Data, Clock	
BROADCAST ORBIT - 7	- Transmission time of message **)	3X,4D19.12
	(sec of GPS week, derived e.g.	
	from Z-count in Hand Over Word (HOW)	
	- Fit interval (hours)	
	(see ICD-GPS-200, 20.3.4.4)	
	Zero if not known	
	- spare	
	- spare	

**) Adjust the Transmission time of message by -604800 to refer to the reported week, if necessary.

*) In order to account for the various compilers, E,e,D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.
Zero-padded two-digit exponents are required, however.

TABLE A5

METEOROLOCICAL DATA FILE - HEADER SECTION DESCRIPTION

HEADER LABEL	DESCRIPTION	FORMAT

	(Columns 61-80)		
	RINEX VERSION / TYPE	- Format version (2.10) - File type ('M' for Meteorological Data)	F9.2,11X, A1,39X
	PGM / RUN BY / DATE	- Name of program creating current file - Name of agency creating current file - Date of file creation	A20, A20, A20
*	COMMENT	Comment line(s)	A60
	MARKER NAME	Station Name (preferably identical to MARKER NAME in the associated Observation File)	A60
*	MARKER NUMBER	Station Number (preferably identical to MARKER NUMBER in the associated Observation File)	A20
	# / TYPES OF OBSERV	- Number of different observation types stored in the file - Observation types The following meteorological observation types are defined in RINEX Version 2: PR : Pressure (mbar) TD : Dry temperature (deg Celsius) HR : Relative Humidity (percent) ZW : Wet zenith path delay (millimeters) (for WVR data) ZD : Dry component of zenith path delay (millimeters) ZT : Total zenith path delay (millimeters) The sequence of the types in this record must correspond to the sequence of the measurements in the data records If more than 9 observation types are being used, use continuation lines with format (6X,9(4X,A2))	I6, 9(4X,A2)
	SENSOR MOD/TYPE/ACC	Description of the met sensor - Model (manufacturer) - Type - Accuracy (same units as obs values) - Observation type Record is repeated for each observation type found in # / TYPES OF OBSERV record	 A20, A20,6X, F7.1,4X, A2,1X
	SENSOR POS XYZ/H	Approximate position of the met sensor - Geocentric coordinates X,Y,Z (ITRF - Ellipsoidal height H or WGS-84) - Observation type Set X,Y,Z to zero if not known. Make sure H refers to ITRF or WGS-84! Record required for barometer, recommended for other sensors.	 3F14.4, 1F14.4, 1X,A2,1X
	END OF HEADER	Last record in the header section.	60X

Records marked with * are optional

TABLE A6

METEOROLOGICAL DATA FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
EPOCH / MET	- Epoch in GPS time (not local time!) year (2 digits, padded with 0 if necessary) month,day,hour,min,sec	1X,I2.2, 5(1X,I2),
	The 2-digit years in RINEX Version 1 and 2.xx files are understood to represent 80-99: 1980-1999 and 00-79: 2000-2079	
	- Met data in the same sequence as given in the header	mF7.1
	More than 8 met data types: Use continuation lines	4X,10F7.1,3X

TABLE A7

GPS OBSERVATION DATA FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           OBSERVATION DATA    M (MIXED)           RINEX VERSION / TYPE
BLANK OR G = GPS,  R = GLONASS,  T = TRANSIT,  M = MIXED    COMMENT
XXRINEXO V9.9       AIUB                24-MAR-01 14:43     PGM / RUN BY / DATE
EXAMPLE OF A MIXED RINEX FILE                               COMMENT
A 9080                                                      MARKER NAME
9080.1.34                                                   MARKER NUMBER
BILL SMITH          ABC INSTITUTE                           OBSERVER / AGENCY
X1234A123           XX                  ZZZ                 REC # / TYPE / VERS
234                 YY                                      ANT # / TYPE
  4375274.       587466.      4589095.                      APPROX POSITION XYZ
        .9030         .0000         .0000                   ANTENNA: DELTA H/E/N
    1     1                                                 WAVELENGTH FACT L1/2
    1     2     6   G14   G15   G16   G17   G18   G19      WAVELENGTH FACT L1/2
    0                                                       RCV CLOCK OFFS APPL
    4    P1    L1    L2    P2                              # / TYPES OF OBSERV
   18.000                                                   INTERVAL
  2001     3    24    13    10   36.0000000                 TIME OF FIRST OBS
                                                           END OF HEADER
 01  3 24 13 10 36.0000000  0  3G12G 9G 6                          -.123456789
  23629347.915           .300 8         -.353    23629364.158
  20891534.648          -.120 9         -.358    20891541.292
  20607600.189          -.430 9          .394    20607605.848
 01  3 24 13 10 50.0000000  4  4
    1     2     2   G 9   G12                                 WAVELENGTH FACT L1/2
  *** WAVELENGTH FACTOR CHANGED FOR 2 SATELLITES ***         COMMENT
      NOW 8 SATELLITES HAVE WL FACT 1 AND 2!                 COMMENT
                                                             COMMENT
 01  3 24 13 10 54.0000000  0  5G12G 9G 6R21R22                    -.123456789
  23619095.450      -53875.632 8    -41981.375    23619112.008
  20886075.667      -28688.027 9    -22354.535    20886082.101
  20611072.689       18247.789 9     14219.770    20611078.410
  21345678.576       12345.567 5
  22123456.789       23456.789 5
 01  3 24 13 11  0.0000000  2  1
           *** FROM NOW ON KINEMATIC DATA! ***               COMMENT
 01  3 24 13 11 48.0000000  0  4G16G12G 9G 6                      -.123456789
  21110991.756       16119.980 7     12560.510    21110998.441
  23588424.398     -215050.557 6   -167571.734    23588439.570
  20869878.790     -113803.187 8    -88677.926    20869884.938
```

```
  20621643.727       73797.462 7     57505.177    20621649.276
                             3  4
A 9080                                                 MARKER NAME
9080.1.34                                              MARKER NUMBER
         .9030         .0000         .0000             ANTENNA: DELTA H/E/N
          --> THIS IS THE START OF A NEW SITE <--      COMMENT
 01  3 24 13 12  6.0000000  0  4G16G12G 6G 9                        -.123456987
  21112589.384       24515.877 6     19102.763 3  21112596.187
  23578228.338     -268624.234 7   -209317.284 4  23578244.398
  20625218.088       92581.207 7     72141.846 4  20625223.795
  20864539.693     -141858.836 8   -110539.435 5  20864545.943
 01  3 24 13 13  1.2345678  5  0
                             4  1
        (AN EVENT FLAG WITH SIGNIFICANT EPOCH)         COMMENT
 01  3 24 13 14 12.0000000  0  4G16G12G 9G 6                         -.123456012
  21124965.133       89551.30216     69779.62654  21124972.2754
  23507272.372     -212616.150 7   -165674.789 5  23507288.421
  20828010.354     -333820.093 6   -260119.395 5  20828017.129
  20650944.902      227775.130 7    177487.651 4  20650950.363
                             4  1
          *** ANTISPOOFING ON G 16 AND LOST LOCK        COMMENT
 01  3 24 13 14 12.0000000  6  2G16G 9
                123456789.0      -9876543.5
                        0.0            -0.5
                             4  2
          ---> CYCLE SLIPS THAT HAVE BEEN APPLIED TO    COMMENT
               THE OBSERVATIONS                         COMMENT
 01  3 24 13 14 48.0000000  0  4G16G12G 9G 6                         -.123456234
  21128884.159      110143.144 7     85825.18545  21128890.7764
  23487131.045     -318463.297 7   -248152.72824  23487146.149
  20817844.743     -387242.571 6   -301747.22925  20817851.322
  20658519.895      267583.67817    208507.26234  20658525.869
                             4  4
         ***   SATELLITE G 9   THIS EPOCH ON WLFACT 1 (L2)  COMMENT
         *** G 6 LOST LOCK AND THIS EPOCH ON WLFACT 2 (L2)  COMMENT
                (OPPOSITE TO PREVIOUS SETTINGS)           COMMENT

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A8
GPS NAVIGATION MESSAGE FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           N: GPS NAV DATA                         RINEX VERSION / TYPE
XXRINEXN V2.10      AIUB                 3-SEP-99 15:22     PGM / RUN BY / DATE
EXAMPLE OF VERSION 2.10 FORMAT                              COMMENT
     .1676D-07   .2235D-07  -.1192D-06  -.1192D-06          ION ALPHA
     .1208D+06   .1310D+06  -.1310D+06  -.1966D+06          ION BETA
     .133179128170D-06  .107469588780D-12   552960     1025 DELTA-UTC: A0,A1,T,W
    13                                                      LEAP SECONDS
                                                            END OF HEADER
 6 99  9  2 17 51 44.0 -.839701388031D-03 -.165982783074D-10  .000000000000D+00
     .910000000000D+02  .934062500000D+02  .116040547840D-08  .162092304801D+00
     .484101474285D-05  .626740418375D-02  .652112066746D-05  .515365489006D+04
     .409904000000D+06 -.242143869400D-07  .329237003460D+00 -.596046447754D-07
     .111541663136D+01  .326593750000D+03  .206958726335D+01 -.638312302555D-08
     .307155651409D-09  .000000000000D+00  .102500000000D+04  .000000000000D+00
     .000000000000D+00  .000000000000D+00  .000000000000D+00  .910000000000D+02
     .406800000000D+06  .000000000000D+00
13 99  9  2 19  0  0.0  .490025617182D-03  .204636307899D-11  .000000000000D+00
     .133000000000D+03 -.963125000000D+02  .146970407622D-08  .292961152146D+01
    -.498816370964D-05  .200239347760D-02  .928156077862D-05  .515328476143D+04
     .414000000000D+06 -.279396772385D-07  .243031939942D+01 -.558793544769D-07
     .110192796930D+01  .271187500000D+03 -.232757915425D+01 -.619632953057D-08
```

```
    -.785747015231D-11  .000000000000D+00  .102500000000D+04  .000000000000D+00
     .000000000000D+00  .000000000000D+00  .000000000000D+00  .389000000000D+03
     .410400000000D+06  .000000000000D+00

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A9
METEOROLOGICAL DATA FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           METEOROLOGICAL DATA                     RINEX VERSION / TYPE
XXRINEXM V9.9       AIUB                 3-APR-96 00:10     PGM / RUN BY / DATE
EXAMPLE OF A MET DATA FILE                                  COMMENT
A 9080                                                      MARKER NAME
     3    PR    TD    HR                                   # / TYPES OF OBSERV
PAROSCIENTIFIC      740-16B                      0.2    PR SENSOR MOD/TYPE/ACC
HAENNI                                           0.1    TD SENSOR MOD/TYPE/ACC
ROTRONIC            I-240W                       5.0    HR SENSOR MOD/TYPE/ACC
        0.0           0.0           0.0        1234.5678 PR SENSOR POS XYZ/H
                                                            END OF HEADER
 96  4  1  0  0 15  987.1   10.6   89.5
 96  4  1  0  0 30  987.2   10.9   90.0
 96  4  1  0  0 45  987.1   11.6   89.0

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A10
GLONASS NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION

	HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT	
	RINEX VERSION / TYPE	- Format version (2.10) - File type ('G' = GLONASS nav mess data)	F9.2,11X, A1,39X	#
	PGM / RUN BY / DATE	- Name of program creating current file - Name of agency creating current file - Date of file creation (dd-mmm-yy hh:mm)	A20, A20, A20	
*	COMMENT	Comment line(s)	A60	*
*	CORR TO SYSTEM TIME	- Time of reference for system time corr (year, month, day) - Correction to system time scale (sec) to correct GLONASS system time to UTC(SU) (-TauC)	 3I6, 3X,D19.12 *)	*
*	LEAP SECONDS	Number of leap seconds since 6-Jan-1980	I6	*
	END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A11
GLONASS NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT

PRN / EPOCH / SV CLK	- Satellite number: Slot number in sat. constellation	I2,
	- Epoch of ephemerides (UTC) - year (2 digits, padded with 0, if necessary) - month,day,hour,minute, - second	1X,I2.2, 4(1X,I2), F5.1,
	- SV clock bias (sec) (-TauN) - SV relative frequency bias (+GammaN) - message frame time (tk) (0 .le. tk .lt. 86400 sec of day UTC) The 2-digit years in RINEX 1 and 2.xx files are understood to represent 80-99: 1980-1999 and 00-79: 2000-2079	D19.12, D19.12, D19.12 *)
BROADCAST ORBIT - 1	- Satellite position X (km) - velocity X dot (km/sec) - X acceleration (km/sec2) - health (0=OK) (Bn)	3X,4D19.12
BROADCAST ORBIT - 2	- Satellite position Y (km) - velocity Y dot (km/sec) - Y acceleration (km/sec2) - frequency number (-7 ... +13)	3X,4D19.12
BROADCAST ORBIT - 3	- Satellite position Z (km) - velocity Z dot (km/sec) - Z acceleration (km/sec2) - Age of oper. information (days) (E)	3X,4D19.12

*) In order to account for the various compilers, E,e,D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.
Zero-padded two-digit exponents are required, however.

TABLE A12

GLONASS NAVIGATION MESSAGE FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           GLONASS NAV DATA                         RINEX VERSION / TYPE
ASRINEXG V1.1.0 VM  AIUB                19-FEB-98 10:42     PGM / RUN BY / DATE
STATION ZIMMERWALD                                          COMMENT
  1998     2    16    0.379979610443D-06                    CORR TO SYSTEM TIME
                                                            END OF HEADER
 3 98  2 15  0 15  0.0 0.163525342941D-03 0.363797880709D-11 0.108000000000D+05
    0.106275903320D+05-0.348924636841D+00 0.931322574615D-09 0.000000000000D+00
   -0.944422070313D+04 0.288163375854D+01 0.931322574615D-09 0.210000000000D+02
    0.212257280273D+05 0.144599342346D+01-0.186264514923D-08 0.300000000000D+01
 4 98  2 15  0 15  0.0 0.179599039257D-03 0.636646291241D-11 0.122400000000D+05
    0.562136621094D+04-0.289074897766D+00-0.931322574615D-09 0.000000000000D+00
   -0.236819248047D+05 0.102263259888D+01 0.931322574615D-09 0.120000000000D+02
    0.762532910156D+04 0.339257907867D+01 0.000000000000D+00 0.300000000000D+01
11 98  2 15  0 15  0.0-0.559808686376D-04-0.272848410532D-11 0.108600000000D+05
   -0.350348437500D+04-0.255325126648D+01 0.931322574615D-09 0.000000000000D+00
    0.106803754883D+05-0.182923507690D+01 0.000000000000D+00 0.400000000000D+01
    0.228762856445D+05 0.447064399719D+00-0.186264514923D-08 0.300000000000D+01
12 98  2 15  0 15  0.0 0.199414789677D-04-0.181898940355D-11 0.108900000000D+05
    0.131731816406D+05-0.143945598602D+01 0.372529029846D-08 0.000000000000D+00
    0.171148715820D+05-0.118937969208D+01 0.931322574615D-09 0.220000000000D+02
    0.135737919922D+05 0.288976097107D+01-0.931322574615D-09 0.300000000000D+01
```

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A13
GLONASS OBSERVATION FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           OBSERVATION DATA    R (GLONASS)         RINEX VERSION / TYPE
XXRINEXO V1.1       AIUB                27-AUG-93 07:23     PGM / RUN BY / DATE
TST1                                                        MARKER NAME
VIEWEG              BRAUNSCHWEIG                            OBSERVER / AGENCY
100                 XX-RECEIVER         1.0                 REC # / TYPE / VERS
101                 XX-ANTENNA                              ANT # / TYPE
  3844808.114    715426.767   5021804.854                  APPROX POSITION XYZ
        1.2340         .0000         .0000                  ANTENNA: DELTA H/E/N
     1     1                                                WAVELENGTH FACT L1/2
     2    C1    L1                                          # / TYPES OF OBSERV
    10.000                                                  INTERVAL
  1993     8    23    14    24   40.0490000     GLO         TIME OF FIRST OBS
                                                            END OF HEADER
 93  8 23 14 24 40.0490000  0  3  2R01R21
  23986839.824       20520.565 5
  23707804.625       19937.231 5
  23834065.096       -9334.581 5
 93  8 23 14 24 50.0490000  0  3  2R01R21
  23992341.033       49856.525 5
  23713141.002       48479.290 5
  23831189.435      -24821.796 5
 93  8 23 14 25   .0490000  0  3  2R01R21
  23997824.854       79217.202 5
  23718494.110       77092.992 5
  23828329.946      -40219.918 5
 93  8 23 14 25 10.0490000  0  5  2R05R17R01R21
  24003328.910      108602.422 5
  24933965.449      -19202.780 5
  22203326.578       -2987.327 5
  23723851.686      105777.849 5
  23825485.526      -55529.205 5
 93  8 23 14 25 20.0490010  0  5  2R05R17R01R21
  24008828.023      138012.178 5
  24927995.616      -51188.500 5
  22202547.907       -7213.298 5
  23729236.758      134533.636 5
  23822662.277      -70749.590 5
 93  8 23 14 25 30.0490000  0  5  2R05R17R01R21
  24014330.779      167446.477 5
  24922041.288      -83151.666 5
  22201767.457      -11388.909 5
  23734633.024      163360.131 5
  23819848.894      -85881.102 5

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A14
MIXED GPS/GLONASS OBSERVATION FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           OBSERVATION DATA    M (MIXED)           RINEX VERSION / TYPE
YYRINEXO V2.8.1 VM  AIUB                 6-FEB-00 13:59     PGM / RUN BY / DATE
TST2                                                        MARKER NAME
001-02-A                                                    MARKER NUMBER
```

```
JIM                 Y-COMPANY                                   OBSERVER / AGENCY
1                   YY-RECEIVER         2.0.1                   REC # / TYPE / VERS
1                   GEODETIC L1                                 ANT # / TYPE
  3851178.1849   -80151.4072  5066671.1013                     APPROX POSITION XYZ
        1.2340        0.0000        0.0000                     ANTENNA: DELTA H/E/N
     1     0                                                    WAVELENGTH FACT L1/2
     2    C1    L1                                            # / TYPES OF OBSERV
    10.000                                                     INTERVAL
    11                                                         LEAP SECONDS
  2000     2     6    11    53    0.0000000     GPS           TIME OF FIRST OBS
                                                               END OF HEADER
 00  2  6 11 53  0.0000000  0 14G23G07G02G05G26G09G21R20R19R12R02R11
                               R10R03
  22576523.586   -11256947.60212
  22360162.704   -16225110.75413
  24484865.974    14662682.882 2
  21950524.331   -13784707.24912
  22507304.252     9846064.848 2
  20148742.213   -20988953.712 4
  22800149.591   -16650822.70012
  19811403.273   -25116169.741 3
  23046997.513    -3264701.688 2
  22778170.622  -821857836.745 1
  22221283.991  -988088156.884 2
  19300913.475   -83282658.19013
  20309075.579  -672668843.84713
  23397403.484  -285457101.34211
 00  2  6 11 53 10.0000000  0 14G23G07G02G05G26G09G21R20R19R12R02R11
                               R10R03
  22578985.016   -11244012.910 2
  22359738.890   -16227337.841 2
  24490324.818    14691368.710 2
  21944376.706   -13817012.849 2
  22512598.731     9873887.580 2
  20147322.111   -20996416.338 4
  22798942.949   -16657163.594 2
  19812513.509   -25110234.795 3
  23053885.702    -3227854.397 2
  22770607.029  -821898566.774 1
  22222967.297  -988079145.989 2
  19297913.736   -83298710.38413
  20313087.618  -672647337.04113
  23392352.454  -285484291.40311

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A15

GEOSTATIONARY NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2.10)	F9.2,11X,
	- File type ('H' = GEO nav mess data)	A1,39X
PGM / RUN BY / DATE	- Name of program creating current file	A20,
	- Name of agency creating current file	A20,
	- Date of file creation (dd-mmm-yy hh:mm)	A20
* COMMENT	Comment line(s)	A60 *
* CORR TO SYSTEM TIME	- Time of reference for system time corr (year, month, day)	3I6, *
	- Correction to transform the GEO system time to UTC (W0)	3X,D19.12 *)

*|LEAP SECONDS	Number of leap seconds since 6-Jan-1980	I6	|*
|END OF HEADER	Last record in the header section.	60X	|

Records marked with * are optional

TABLE A16

GEOSTATIONARY NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite number (PRN - 100)	I2,
	- Epoch of ephemerides (GPS) (Toe)	
	- year (2 digits, padded with 0 if necessary)	1X,I2.2,
	- month,day,hour,minute,	4(1X,I2),
	- second	F5.1,
	- SV clock bias (sec) (aGf0)	D19.12,
	- SV relative frequency bias (aGf1)	D19.12,
	- message frame time (sec of day GPS)	D19.12
BROADCAST ORBIT - 1	- Satellite position X (km)	3X,4D19.12
	- velocity X dot (km/sec)	
	- X acceleration (km/sec2)	*)
	- health (0=OK)	
BROADCAST ORBIT - 2	- Satellite position Y (km)	3X,4D19.12
	- velocity Y dot (km/sec)	
	- Y acceleration (km/sec2)	
	- Accuracy code (URA, meters)	
BROADCAST ORBIT - 3	- Satellite position Z (km)	3X,4D19.12
	- velocity Z dot (km/sec)	
	- Z acceleration (km/sec2)	
	- spare	

*) In order to account for the various compilers, E,e,D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.
Zero-padded two-digit exponents are required, however.

TABLE A17

MIXED GPS/GEO OBSERVATION FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           OBSERVATION DATA    M (MIXED)           RINEX VERSION / TYPE
RinExp V.2.0.2      TESTUSER            00-02-04 09:30      PGM / RUN BY / DATE
                                                            COMMENT
The file contains L1 pseudorange and phase data of the      COMMENT
geostationary AOR-E satellite (PRN 120 = S20)               COMMENT
                                                            COMMENT
TLSE D                                                      MARKER NAME
ESTB                TESTAGENCY                              OBSERVER / AGENCY
SGL98030069         Novatel Millennium  HW3-1 SW 4.45/2.3   REC # / TYPE / VERS
                    ASH701073.1                             ANT # / TYPE
  4629365.0750   112100.1790  4371619.4160                  APPROX POSITION XYZ
        0.0000        0.0000        0.0000                  ANTENNA: DELTA H/E/N
     1     1                                                WAVELENGTH FACT L1/2
     4    C1    L1    L2    P2                              # / TYPES OF OBSERV
```

```
     1                                                      INTERVAL
  2000     1    13    14    45    0.000000      GPS         TIME OF FIRST OBS
  2000     1    13    15     0    0.000000      GPS         TIME OF LAST OBS
     0                                                      RCV CLOCK OFFS APPL
                                                            END OF HEADER
 00 01 13 14 45  0.0000000  0  8G25G17G06G05G24G29G30S20             0.000535140
  21839900.207     -236148.877 9   -184047.71049  21839901.4384
  25151926.413     -161002.900 9   -125509.72447  25151935.8274
  20531103.515      763336.059 9    594797.53149  20531105.0114
  23001624.801     -432989.642 9   -337436.50348  23001628.1684
  23610349.510     -384890.728 9   -299952.38848  23610354.3504
  23954474.398     -151982.173 9   -118480.96847  23954481.1994
  20622367.016     -332628.466 9   -259214.55249  20622367.8754
  38137559.506      335849.135 9
 00 01 13 14 45  1.0000000  0  8G25G17G06G05G24G29G30S20             0.000535144
  21839500.278     -238250.743 9   -185685.52549  21839501.4814
  25151246.148     -164576.503 9   -128294.33947  25151256.2614
  20531084.382      763235.849 9    594719.44849  20531085.8784
  23002123.430     -430369.237 9   -335394.62748  23002126.7114
  23610670.127     -383205.864 9   -298639.51048  23610674.9834
  23955051.773     -148948.417 9   -116117.00748  23955058.5034
  20622558.579     -331621.765 9   -258430.11049  20622559.4574
  38137558.783      335846.284 9
 00 01 13 14 45  2.0000000  0  8G25G17G06G05G24G29G30S20             0.000535144
  21839100.418     -240352.173 9   -187323.00449  21839101.6534
  25150565.890     -168150.148 9   -131078.97647  25150576.2144
  20531065.378      763136.116 9    594641.73549  20531066.8984
  23002622.082     -427748.683 9   -333352.63648  23002625.3444
  23610990.819     -381520.461 9   -297326.20848  23610995.8424
  23955629.062     -145914.531 9   -113752.94748  23955636.5544
  20622750.161     -330614.723 9   -257645.40149  20622751.0554
  38137558.365      335843.457 9

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

TABLE A18

GEO NAVIGATION MESSAGE FILE - EXAMPLE

```
----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

     2.10           H: GEO NAV MSG DATA                    RINEX VERSION / TYPE
SuP v. 1.4          TESTUSER            04-02-00 10:04     PGM / RUN BY / DATE
                                                           COMMENT
The file contains navigation message data of the           COMMENT
geostationary AOR-E satellite (PRN 120 = S20)              COMMENT
                                                           COMMENT
                                                           END OF HEADER
20 00 01 13 14 46 24.0  .209547579288D-07 -.545696821064D-11  .532351280000D+05
     .406131052800D+08  .150625000000D+01  .875000000000D-04  .000000000000D+00
    -.112454290400D+08  .308125000000D+01 -.112500000000D-03  .400000000000D+01
     .781616000000D+05  .959600000000D+01 -.437500000000D-03  .000000000000D+00
20 00 01 13 14 48 00.0  .204890966415D-07 -.545696821064D-11  .533161280000D+05
     .406132503200D+08  .151500000000D+01  .875000000000D-04  .000000000000D+00
    -.112451338400D+08  .307000000000D+01 -.125000000000D-03  .400000000000D+01
     .790812000000D+05  .955600000000D+01 -.437500000000D-03  .000000000000D+00
20 00 01 13 14 49 36.0  .195577740669D-07 -.545696821064D-11  .533981280000D+05
     .406133961600D+08  .152375000000D+01  .875000000000D-04  .000000000000D+00
    -.112448396800D+08  .305875000000D+01 -.125000000000D-03  .400000000000D+01
     .799968000000D+05  .951600000000D+01 -.437500000000D-03  .000000000000D+00
20 00 01 13 14 51 12.0  .190921127796D-07 -.545696821064D-11  .534791280000D+05
     .406135428800D+08  .153250000000D+01  .875000000000D-04  .000000000000D+00
    -.112445465600D+08  .304687500000D+01 -.125000000000D-03  .400000000000D+01
     .809084000000D+05  .947600000000D+01 -.437500000000D-03  .000000000000D+00

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|
```

ANEXO 9 –Descrição do formato SP3 de efemérides precisas.

The National Geodetic Survey Standard GPS Format SP3

Paul R. Spofford
National Geodetic Survey
National Ocean Service, NOAA
Silver Spring, MD 20910-3282, USA

and

Benjamin W. Remondi, PhD
P.O. Box 37
Dickerson, Maryland 20842, USA

INTRODUCTION

Why do we need standardized orbit formats? Standard orbit formats provide many advantages, the most obvious being orbit exchange. ASCII and binary formats both satisfy this function, but ASCII does it with greater generality because binary formats are computer operating system dependent.

The NGS standard GPS orbit format SP1 was introduced in Remondi (1985). After a few years of use, it was realized that enhancements would eventually be required. The "orbit type," the coordinate system, and the GPS week associated with the first epoch of the ephemeris file were added in a manner that did not impact the formats and existing software.

A more serious omission of the initial NGS orbit format was the satellite clock corrections. This omission reflected an earlier belief that all geodetic applications could be accomplished in differential mode. Today we realize that standard formats serve a wider community and include those who find it inconvenient to operate in a differential mode. A user can operate in single-receiver or navigation mode based on the broadcast message. However, the user can get more accurate (post-processed) results if the precise orbital data and the associated satellite clock corrections, which were determined simultaneously with those precise orbits, are available. This becomes even more valuable when the broadcast orbit and clock information are intentionally degraded.

Thus, a new NGS orbit format was proposed in Remondi (1989), and modified and adopted in Remondi (1991). This format is similar to the original NGS orbit format, but comprises positional and satellite clock correction data. Furthermore, other changes were proposed which allow more flexibility with regard to enhancements. This summary document combines the specifications and enhancements discussed in Remondi (1989) and Remondi (1991), with examples for the benefit of the user.

SP3

In this document the NGS orbital format SP3 (Standard Product # 3) for Global Positioning System (GPS) satellites is discussed (see examples 1 and 2). The major addition to earlier formats is the satellite clock correction information which is computed simultaneously with the orbits. The basic format is a position and clock record; a second, optional, record contains velocities and clock rates-of-change. The Position Record Flag, P, in line one indicates that no velocities are included. The Velocity Record Flag, V, in line one indicates that at each epoch, and for each satellite, a satellite velocity and clock rate-of-change has been computed. The SP3 format has been designed such that satellites other than GPS could be described as well.

Note: All times referred to in this document are GPS times, even when they are represented as Gregorian or Modified Julian Dates. Thus, information for conversion of GPS time to Coordinated Universal Time (UTC) is not provided as part of the SP3 format.

```
!     Standard Product #3 ASCII SP3 Format Version "a"
```

(refer to example given in figure 1)

SP3 First Line

Columns 1-2	Version Symbol	#a
Column 3	Pos or Vel Flag	P or V
Columns 4-7	Year Start	1994
Column 8	Unused	_
Columns 9-10	Month Start	12
Column 11	Unused	_
Columns 12-13	Day of Month St	17
Column 14	Unused	_
Columns 15-16	Hour Start	_0
Column 17	Unused	_
Columns 18-19	Minute Start	_0
Column 20	Unused	_
Columns 21-31	Second Start	_0.00000000
Column 32	Unused	_
Columns 33-39	Number of Epochs	_____96
Column 40	Unused	_
Columns 41-45	Data Used	____d
Column 46	Unused	_
Columns 47-51	Coordinate Sys	ITR92
Column 52	Unused	_
Columns 53-55	Orbit Type	FIT
Column 56	Unused	_
Columns 57-60	Agency	_NGS

SP3 Line Two

Columns 1-2	Symbols	##
Column 3	Unused	_
Columns 4-7	GPS Week	_779
Column 8	Unused	_
Columns 9-23	Seconds of Week	518400.00000000
Column 24	Unused	_
Columns 25-38	Epoch Interval	__900.00000000
Column 39	Unused	_
Columns 40-44	Mod Jul Day St	49703

```
Column  45          Unused                  _
Columns 46-60       Fractional Day   0.0000000000000


SP3 Line Three

Columns 1-2         Symbols          +_
Column  3-4         Unused           __
Columns 5-6         Number of Sats   25
Column  7-9         Unused           __
Columns 10-12       Sat #1 Id        __1
Column  13-15       Sat #2 Id        __2
       *
       *
       *
Columns 58-60       Sat #17 Id      _22

SP3 Line Four

Columns 1-2         Symbols          +_
Columns 3-9         Unused           _______
Columns 10-12       Sat #18 Id       _23
Columns 13-15       Sat #19 Id       _24
       *
       *
       *
Columns 58-60       Sat #34 Id       __0


SP3 Line Five

Columns 1-2         Symbols          +_
Columns 3-9         Unused           _______
Columns 10-12       Sat #35 Id       __0
Columns 13-15       Sat #36 Id       __0
       *
       *
       *
Columns 58-60       Sat #51 Id       __0


SP3 Line Six

Columns 1-2         Symbols          +_
Columns 3-9         Unused           _______
Columns 10-12       Sat #52 Id       __0
Columns 13-15       Sat #53 Id       __0
       *
       *
       *
Columns 58-60       Sat #68 Id      __0


SP3 Line Seven

Columns 1-2         Symbols          +_
Columns 3-9         Unused           _______
Columns 10-12       Sat #69 Id       __0
Columns 13-15       Sat #70 Id       __0
       *
       *
```

```
       *
Columns 58-60       Sat #85 Id       __0


SP3 Line Eight

Columns 1-2         Symbols          ++
Columns 3-9         Unused           _______
Columns 10-12       Sat #1 Accuracy  __7
Columns 13-15       Sat #2 Accuracy  __6
       *
       *
       *
Columns 58-60       Sat #17 Accuracy __5


SP3 Line Nine

Columns 1-2         Symbols          ++
Columns 3-9         Unused           _______
Columns 10-12       Sat #18 Accuracy __5
Columns 13-15       Sat #19 Accuracy __5
       *
       *
       *
Columns 58-60       Sat #34 Accuracy __0


SP3 Line Ten

Columns 1-2         Symbols          ++
Columns 3-9         Unused           _______
Columns 10-12       Sat #35 Accuracy __0
Columns 13-15       Sat #36 Accuracy __0
       *
       *
       *
Columns 58-60       Sat #51 Accuracy __0


SP3 Line Eleven

Columns 1-2         Symbols          ++
Columns 3-9         Unused           _______
Columns 10-12       Sat #52 Accuracy __0
Columns 13-15       Sat #53 Accuracy __0
       *
       *
       *
Columns 58-60       Sat #68 Accuracy __0


SP3 Line Twelve

Columns 1-2         Symbols          ++
Columns 3-9         Unused           _______
Columns 10-12       Sat #69 Accuracy __0
Columns 13-15       Sat #70 Accuracy __0
       *
       *
       *
```

```
Columns 58-60       Sat #85 Accuracy __0


SP3 Lines Thirteen and Fourteen

Columns 1-2         Symbols          %c
Column  3           Unused           _
Columns 4-5         2 characters     cc
Column  6           Unused           _
Columns 7-8         2 characters     cc
Column  9           Unused           _
Columns 10-12       3 characters     ccc
Column  13          Unused           _
Columns 14-16       3 characters     ccc
Column  17          Unused           _
Columns 18-21       4 characters     cccc
Column  22          Unused           _
Columns 23-26       4 characters     cccc
Column  27          Unused           _
Columns 28-31       4 characters     cccc
Column  32          Unused           _
Columns 33-36       4 characters     cccc
Column  37          Unused           _
Columns 38-42       5 characters     ccccc
Column  43          Unused           _
Columns 44-48       5 characters     ccccc
Column  49          Unused           _
Columns 50-54       5 characters     ccccc
Column  55          Unused           _
Columns 56-60       5 characters     ccccc


SP3 Lines Fifteen and Sixteen

Columns 1-2         Symbols          %f
Column  3           Unused           _
Columns 4-13        10-column float  _0.0000000
Column  14          Unused           _
Columns 15-26       12-column float  _0.000000000
Column  27          Unused           _
Columns 28-41       14-column float  _0.00000000000
Column  42          Unused           _
Columns 43-60       18-column float  _0.000000000000000


SP3 Lines Seventeen and Eighteen

Columns 1-2         Symbols          %i
Column  3           Unused           _
Columns 4-7         4-column int     ___0
Column  8           Unused           _
Columns 9-12        4-column int     ___0
Column  13          Unused           _
Columns 14-17       4-column int     ___0
Column  18          Unused           _
Columns 19-22       4-column int     ___0
Column  23          Unused           _
Columns 24-29       6-column int     _____0
Column  30          Unused           _
Columns 31-36       6-column int     _____0
Column  37          Unused           _
```

```
Columns 38-43       6-column int     _____0
Column  44          Unused           _
Columns 45-50       6-column int     _____0
Column  51          Unused           _
Columns 52-60       9-column int     ________0
```

SP3 Lines Nineteen to Twenty two

```
Columns 1-2         Symbols          /*
Column  3           Unused           _
Columns 4-60        Comment          CC...CC
```

SP3 Line Twenty three (The Epoch Header Record)

```
Columns 1-2         Symbols          *_
Column  3           Unused           _
Columns 4-7         Year Start       1994
Column  8           Unused           _
Columns 9-10        Month Start      12
Column  11          Unused           _
Columns 12-13       Day of Month St  17
Column  14          Unused           _
Columns 15-16       Hour Start       _0
Column  17          Unused           _
Columns 18-19       Minute Start     _0
Column  20          Unused           _
Columns 21-31       Second Start     _0.00000000
```

SP3 Line Twenty four (The Position and Clock Record)
(See example 1)

```
Column 1            Symbol           P
Columns 2-4         Vehicle Id.      __1
Columns 5-18        x-coordinate(km) __16258.524750
Columns 33-46       y-coordinate(km) __-3529.015750
Columns 33-46       z-coordinate(km) _-20611.427050
Columns 47-60       clock (microsec) ____-62.540600
     *
     *
     *
```

In addition, one could use the Velocity and Clock Rate-of-Change record, V, after the Position and Clock record. The clock rate-of-change units are 10**-4 microseconds/second.

SP3 Line Twenty five
(See example 2)

```
Column 1            Symbol           V
Columns 2-4         Vehicle Id.      __1
Columns 5-18        x-velocity(dm/s) __16258.524750
Columns 19-32       y-velocity(dm/s) __-3529.015750
Columns 33-46       z-velocity(dm/s) _-20611.427050
Columns 47-60       clock rate-chg   ____-62.540600
     *
     *
     *
```

```
     SP3 Line 22+NUMEPS*(NUMSATS+1)+1 (i.e., The Last Line)

     Columns 1-3         Symbols          EOF

!Discussion of the SP3 Format
```

On line one, character two is the format version identification character. The first released version has been designated version 'a'. Subsequent versions will use lower case letters in alphabetical order. The first line comprises the Gregorian date and time of day of the first epoch of the orbit, the number of epochs in the ephemeris file (up to 10 million), the data used descriptor, the orbit type descriptor, and the agency descriptor. The data used descriptor was included for ease in distinguishing between multiple orbital solutions from a single organization. This will have primary use for the agency generating the orbit. A possible convention is given below; this is not considered final and suggestions are welcome.

```
     u   -- undifferenced carrier phase
     du  -- change in u with time
     s   -- 2-receiver/1-satellite carrier phase
     ds  -- change on s with time
     d   -- 2-receiver/2-satellite carrier phase
     dd  -- change in d with time
     U   -- undifferenced code phase
     dU  -- change in U with time
     S   -- 2-receiver/1-satellite code phase
     dS  -- change in S with time
     D   -- 2-receiver/2-satellite code phase
     dD  -- change in D with time
      +  -- type separator
```

Combinations such as "__u+U" seem reasonable. If the measurements used were complex combinations of standard types, then one could use "mixed" where mixed could be explained on the comment lines.

Orbit type is described by a three character descriptor. At this time only three have been defined: FIT (fitted), EXT (extrapolated or predicted), and BCT (broadcast). Naturally, others are possible. The computing agency descriptor allows four characters (e.g. _NGS).

The second line has: the GPS week (which will exceed 1000 in the year 1999); the seconds of the GPS Week elapsed at the start of the orbit (0.0 <= seconds of week < 604800.0); the epoch interval (0.0 < epoch interval < 100000.0) in seconds; the modified Julian Day Start (where 44244 represents GPS zero time -- January 6, 1980); and fractional part of the day (0.0 <= fractional < 1.0) at the start of the orbit.

The third line to the seventh lines indicate the number of satellites followed by their respective identifiers. The identifiers must use consecutive slots and continue on lines 4-7, if required. The value 0 should only appear after all the identifiers are listed. Satellite identifiers may be listed in any order. However, for ease in reviewing satellites included in the orbit file it is recommended that numerical order be used.

The eighth line to the twelfth lines have the orbit accuracy exponents. The value 0 is interpreted as accuracy unknown. A satellite's accuracy exponent appears in the same slot on lines 8-12 as the identifier on lines 3-7. The accuracy is computed from the exponent as in the following example. If the accuracy exponent is 13, the accuracy is 2**13 mm or 8 m. The quoted orbital error should represent one standard deviation and be based on the orbital error in the entire file for the respective satellite. This may lead to some distortion when orbit files are joined together.

Lines 13-18 allow the SP3 ASCII file to be modified, since the SP3 format has been designed so that additional parameters may be added.

Lines 19-22 are free form comments.

Line 23 is the epoch header date and time.

Line 24 is the position and clock line, and the first character is 'P' indicating a position line. The positional values are in kilometers and are precise to 1 mm. A precision of 0.5 mm can be accommodated if rounding is used, i.e., the value shown is never more than 0.5 mm from the computed value. The clock values are in microseconds and are precise to 1 picosecond. Bad or absent positional values are to be set to 0.000000. Bad or absent clock values are to be set to _999999.9999__. The six integer nines are required, whereas the fractional part nines are optional. When the position/velocity mode flag is set to 'V' in line one, each position record for a given satellite is followed by a velocity record for the same satellite. The first character of the velocity record is a "V". The velocity components are given in decimeters/second and have a precision of 10**-4 mm/second. The last column of a velocity record is the rate-of-change of clock correction given in units of 10**-4 microsecond/second. The precision of this parameter is 10**-16 second/second.

```
!Example 1

#aP1994 12 17  0  0  0.00000000      96     d ITR92 FIT  NGS
##  779 518400.00000000   900.00000000 49703 0.0000000000000
+   25     1  2  4  5  6  7  9 12 14 15 16 17 18 19 20 21 22
+         23 24 25 26 27 28 29 31  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         7  6  5  5  5  5  5  5  5  6  5  5  5  5  6  5  5
++         5  5  6  5  5  5  5  5  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
%c cc cc ccc ccc cccc cccc cccc cccc cccc ccccc ccccc ccccc ccccc
%c cc cc ccc ccc cccc cccc cccc cccc cccc ccccc ccccc ccccc ccccc
%f  0.0000000  0.000000000  0.00000000000  0.000000000000000
%f  0.0000000  0.000000000  0.00000000000  0.000000000000000
%i    0    0    0    0      0      0      0      0         0
%i    0    0    0    0      0      0      0      0         0
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
```

```
*  1994 12 17  0  0  0.00000000
P  1  16258.524750  -3529.015750 -20611.427050    -62.540600
P  2 -21998.652100  -8922.093550 -12229.824050   -131.326200
P  4 -26019.547600   4809.810900  -2508.578200      3.544600
P  5   7014.950200  21130.960300 -14387.334650     79.692800
   *
   *
   *
P 28  13204.937750 -20485.533400  10794.787000     55.200800
P 29  -1638.431050 -24391.479200  10455.312650      3.690300
P 31   6265.255800 -25687.986950   -753.359000     70.830800
*  1994 12 17  0 15  0.00000000
P  1  15716.820135  -1169.850490 -21281.578766    -62.542746
P  2 -22813.261065  -9927.616864  -9816.490189   -131.328686
   *
   *
   *
P 28  13416.746195 -22186.753441   6248.864499     55.385492
P 29  -2745.269113 -22169.709690  14469.340453      3.718873
P 31   5629.986510 -25241.323751  -5659.769347     71.118497
*  1994 12 17 23 45  0.00000000
P  1  16708.907949  -5150.972262 -19904.291167    -62.727331
P  2 -21321.617042  -8048.187511 -13856.581227   -131.555527
P  4 -26107.382526   5010.736034   -422.963345      3.672587
P  5   7932.078481  21838.230749 -12767.671968     79.888744
   *
   *
   *
P 28  13308.321924 -21306.183480   8935.290694     55.387446
P 29  -2059.774801 -23532.083663  12229.852140      3.719337
P 31   6034.395625 -25605.621951  -2843.783172     71.121661
EOF!Example 2

#aV1994 12 17  0  0  0.00000000      96     d ITR92 FIT  NGS
##  779 518400.00000000   900.00000000 49703 0.0000000000000
+   25     1  2  4  5  6  7  9 12 14 15 16 17 18 19 20 21 22
+         23 24 25 26 27 28 29 31  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
+          0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         7  6  5  5  5  5  5  5  5  6  5  5  5  5  6  5  5
++         5  5  6  5  5  5  5  5  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
++         0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
%c cc cc ccc ccc cccc cccc cccc cccc ccccc ccccc ccccc ccccc
%c cc cc ccc ccc cccc cccc cccc cccc ccccc ccccc ccccc ccccc
%f  0.0000000  0.000000000  0.00000000000  0.000000000000000
%f  0.0000000  0.000000000  0.00000000000  0.000000000000000
%i    0    0    0    0      0      0      0      0         0
%i    0    0    0    0      0      0      0      0         0
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
/* CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
*  1994 12 17  0  0  0.00000000
P  1  16258.524750  -3529.015750 -20611.427050    -62.540600
V  1  -6560.373522  25605.954994  -9460.427179     -0.024236
P  2 -21998.652100  -8922.093550 -12229.824050   -131.326200
V  2  -9852.750736 -12435.176313  25738.634180     -0.029422
P  4 -26019.547600   4809.810900  -2508.578200      3.544600
```

```
V  4   2559.038002  -3340.527442 -31621.490838      0.016744
   *
   *
   *
P 29  -1638.431050 -24391.479200  10455.312650      3.690300
V 29   5754.005457 -12065.761570 -27707.056273      0.003537
P 31   6265.255800 -25687.986950   -753.359000     70.830800
V 31   3053.344058    -63.091750  31910.454757      0.033749
*  1994 12 17  0 15  0.00000000
P  1  15716.820135  -1169.850490 -21281.578766    -62.542746
V  1  -5439.955846  26738.341429  -5409.793390     -0.023226
P  2 -22813.261065  -9927.616864  -9816.490189   -131.328686
V  2  -8178.974330  -9924.329320  27813.754308     -0.025238
   *
   *
   *
P 31   5629.986510 -25241.323751  -5659.769347     71.118497
V 31   5213.646243  -5585.922919  30831.379942      0.040199
*  1994 12 17 23 45  0.00000000
P  1  16708.907949  -5150.972262 -19904.291167    -62.727331
V  1  -7218.304166  24494.550676 -12283.334526     -0.023824
   *
   *
   *
P 31   6034.395625 -25605.621951  -2843.783172     71.121661
V 31   3831.346050  -2469.229615  31655.436179      0.028935
EOF!
```

REFERENCES

1. Remondi, B. W. 1985: Distribution of Global Positioning System Ephemerides by the National Geodetic Survey, Presented at the First Conference on Civil Applications of GPS - Institute of Navigation, September 12, 1985, 8 pp.
2. Remondi, B. W. 1989: Extending the National Geodetic Survey Geodetic Orbit Formats, NOAA Technical Report 133 NGS 46, 85 pp.
3. Remondi, B. W., 1991: NGS Second Generation ASCII and Binary Orbit Formats and Associated Interpolated Studies, Proceedings of the Twentieth General Assembly, International Union of Geodesy and Geophysics, Vienna, Austria, August 11-24, 1991, 28 pp.

ORDERING INFORMATION

Geodetic publications of NOAA and the National Geodetic Survey are sold in paper form by the Information Services Division, National Geodetic Survey, NOAA. To obtain a price list or to place an order contact:

NOAA, National Geodetic Survey
SSMC3, N/CG112
1315 East-West Highway
Silver Spring, Maryland 20910-3282
USA
Telephone: 301-713-3242
FAX: 301-713-4172.

Paul R. Spofford — Internet: pauls@ngs.noaa.gov
NOAA, National Geodetic Survey — Telephone: 301-713-3205
1315 East-West Highway, N/CG12 — FAX: 301-713-4322
Silver Spring, Maryland 20910-3282, USA — Home: 301-831-6099